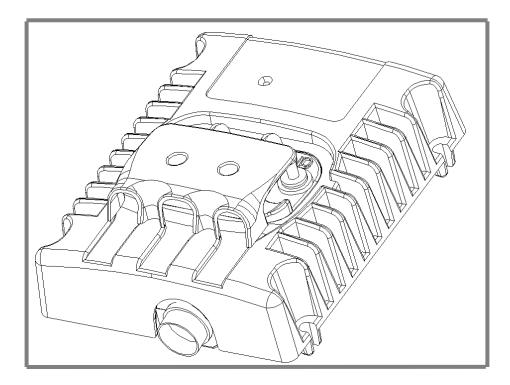
## VANN-Bus 80-Series

# Power Management System With Model Based Battery Monitoring



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### **Notes**

### Introduction

Thank you for purchasing a Vanner VANN-Bus CAN Power Management System. We are confident that you will be very pleased with its performance because our 80-Series are designed and manufactured by skilled professionals using the highest standards in workmanship. With minimum maintenance and care, you can be assured of many years of trouble free service.

### **General Description**

The Vanner VANN-Bus CAN Power Management System is an efficient and highly reliable method of obtaining a 12 volt DC power source from a 24 volt DC electrical system. The VANN-Bus makes the batteries look like they are in series and parallel at the same time. In addition to providing regulated 12 volt power, the system ensures that battery voltages remain equal which significantly extends battery life. Ideally suited for vehicle and alternate energy applications, the VANN-Bus is designed to save your batteries and the money you would spend replacing them. Users of the Vanner VANN-Bus know that it is the most cost effective and dependable solution for dual voltage systems.

The CAN (Controller Area Network) Capable Smart Monitor is a device designed to monitor and report the status of several critical functions in the vehicle electrical system. This unit provides real-time fault signals over the CAN bus to the vehicle electrical system controller. Fault indications can then be given from the vehicle's electrical system controller. Battery-monitoring algorithms have been incorporated into the 80-Series VANN-Bus, transmitting real time battery state of charge, state of health, and run time messages over CAN.

A typical system would include a 24VDC power source, such as an alternator or solar array, two 12 volt battery banks in series, and the *VANN-Bus*. The *VANN-Bus* connects to the 24 volt, 12 volt and ground terminals of the battery system. When the 12 volt loads require power, the *VANN-Bus* ensures that the current is taken equally from both batteries, and that the voltages of the two batteries are kept equal. This equalization ensures extended battery life and provides a stable 12 volt supply for operating accessories.

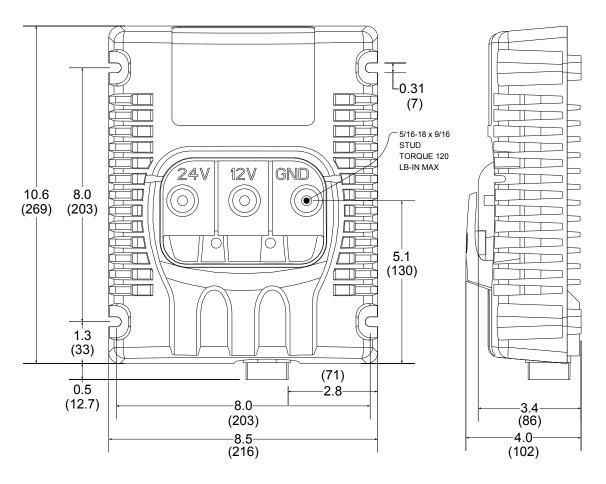
**Paralleling VANN-Bus:** Models are available which provide 60, 80 and 100 amps of 12 volt DC power. *VANN-Bus* may also be operated in parallel to provide more power. For example, two 60 amp units can be installed to provide 120 amps of 12 volt DC power.

**NOTE:** The Vanner *VANN-Bus CAN Power Management System* is an extremely reliable device and, when installed according to the instructions, will provide reliable operation for an indefinite period of time. However, if a system abnormality should develop that would cause a *VANN-Bus* malfunction, damage to the battery system could result if 12 volt loads are present.

**Specifications** 

80-Series CAN Equalizers				
Model Number	80-60CAN	80-80CAN	80-100CAN	
Input Voltage 24v	18 to 32 v			
Efficiency (Peak)	>97%	>97%	>97%	
Max 24v Input Amps	32	43	53	
Output Voltage	(Input Voltage/2) ±2%			
Output Amps (12v)	0-60	0-80	0-100	
Standby Current	20 milliamps nominal at 28.4V			
Smart Monitor	Alarm Low/High Voltage, Imbalance, Undervoltage protect override, VANN-Bus fault Battery Monitoring			
Operating Temp.	-40°C to +75°C (-40°F to 167°F)			
Storage Temp.	-54°C to +95°C (-65°F to 203°F)			
Serviceable	Yes	Yes	Yes	
Environmental Considerations	Cast aluminum enclosure provides protection against salt, fungus, dust, water, fuel vapors and all fluids associated with commercial and off-highway vehicle operations. IP rated 56.			
Mounting Location	Mount on a flat surface close to the batteries to allow short cable runs. Location should be protected from battery acid and gases.			
Weights	8.7 lbs.	8.9 lbs.	9.3 lbs.	

### **80-Series CAN Dimensional Specifications**



#### **Theory of Operation** F2 +24V **Dual Current** Sensor 80/600A 12 V +24V Battery B VANN-Guard F1 +12V --O-+12∨ Single Current Temperature Sensor 80A Sensor +12 Volt **GND** Loads +24 Volt 12 V 24V Alt Battery A Loads

In many 24 volt electrical systems it is desirable to tap into the battery system to obtain power for 12 volt loads. This method, while seemingly simple, causes a charge imbalance resulting in Battery B (see diagram) being overcharged, and possibly boiling, while Battery A discharges.

To solve this application problem the Vanner *VANN-Bus* is connected to the battery system at the +24 volt, +12 volt, and ground points. The *VANN-Bus* makes the batteries look like they are in series and in parallel at the same time. The *VANN-Bus* maintains the voltage balance and therefore the charge acceptance rate of each battery. The *VANN-Bus* holds the Battery A and B voltages to within 0.05 volts under light loads and to within 0.1 volts at full rated load.

When the voltage of Battery A is higher than or equal to Battery B the *VANN-Bus* is in the standby mode, i.e., it is not transferring power from its 24 volt input to its 12 volt output. When a 12 volt load is present, and Battery A's voltage decreases to just below the voltage of Battery B, the *VANN-Bus* activates and transfers sufficient current from Battery B to Battery A to satisfy the load and maintain an equal voltage and charge in both batteries.

A key advantage of a system containing a Vanner *VANN-Bus*, compared to a DC to DC converter, is that if the 12 volt load requires a momentary surge current which exceeds the rated capacity of the *VANN-Bus*, Battery A will supply the extra current to the load. The *VANN-Bus* will then replenish the energy to Battery A after the surge has passed.

The following scenarios describe the VANN-Bus CAN Power Management System operation.

**Scenario #1 - 24 volt load present, no 12 volt load present.** The system operates as a system would without the *VANN-Bus* whether the alternator is ON or OFF. The *VANN-Bus* is in the standby mode except for making small adjustments to keep the batteries in balance.

**Scenario #2 - Both 24 volt and 12 volt loads present, alternator is OFF.** The *VANN-Bus* will insure that both batteries will discharge at the same rate even if different loads are present.

**Scenario # 3 - Both 24 volt and 12 volt loads present, alternator is ON.** The alternator provides 24 volt power to the battery system and to the 24 volt loads. The *VANN-Bus* transfers power from the 24 volt source to the 12 volt load by converting 24 volt power to 12 volts. It will supply sufficient 12 volt power to satisfy the 12 volt load and to maintain battery voltage balance.

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### **Smart Monitor Functionality**

All functionality described in this section requires that the Monitor Ignition Input (Terminal B) be connected to +24v in order to be active. Please see the above figure for placement of the current and temperature sensors.

#### A. Switched Sensor Supply Output

This output is used to provide +5v for the Vanner Smart Sensor<sup>™</sup> and current sensors. The +5v output is switched for low power shutdown and sleep mode operation.

#### B. Smart Monitor Ignition (Enable) Input

This input powers the equalizer monitor. When this pin is taken to +24V the monitor becomes active.

#### C. CAN Shield

This connection is used to make common the shield on the CAN cable. This is required for noise considerations in vehicle electrical systems.

#### D. CAN Low

This is the connection for the vehicle's public CAN bus. The Smart Monitor will communicate faults to the vehicle's electrical system controller via the CAN bus.

#### E. CAN High

This is the connection for the vehicle's public CAN bus. The Smart Monitor will communicate faults to the vehicle's electrical system controller via the CAN bus.

### F. Not Connected on Standard Equalizers/Low State of Charge (SOC) Disconnect for Equalizers with -LVD Option

This pin is not currently used on Standard Equalizers.

For equalizers with the -LVD option, a +24V/3A pulse is provided for 500mS. See page 7 for additional details regarding this output.

#### G. Dual Current Sensor, High Range Output (+24V)

The monitor can record high amperage cranking current (up to 600A) on the +24V battery bank. The high current output of the dual current sensor should be connected to this input.

#### H. Sensor Ground

Connect ground for current sensors and Smart Sensors here.

#### J. Dual Current Sensor, Low Range Output (+24V)

The monitor can record the low amperage incoming and outgoing battery current on the +24V battery bank. The low range output of the dual current sensor should be connected to this input.

#### K. Single Current Sensor (+12V) Signal Input

The monitor can record incoming and outgoing battery current on the lower battery. The output from the current sensor monitoring the +12v output line should be connected to this input.

#### L. Temperature Sensor

The monitor can record the temperate of the batteries. The output from the temperature sensor should be connected to this input.

#### M. +24V Battery Remote Sense

If this pin is connected directly to the +24V battery positive by a separate line, it will improve the accuracy of the Equalizer balance of the batteries when load current is drawn. See below for more information.

#### N. +12V Battery Remote Sense

If this pin is connected directly to the +12V battery positive by a separate line, it will improve the accuracy of the Equalizer balance of the batteries when load current is drawn. See below for more information.

#### P. Battery Ground Remote Sense

If this pin is connected directly to the battery ground by a separate line, it will improve the accuracy of the Equalizer balance of the batteries when load current is drawn. See below for more information.

Deutsch Connector Pin Out

helow

#### Sensor Supply +24V Ignition Input CAN Shield С CAN Low +24V 12 V Battery B VANN-Guard **CAN High** +12V \* Spare or Low SOC Output --O +12∨ Dual Current Sensor, High +12 Volt +24 Volt 12 V Sensor Ground Loads **GND** Battery A Alt Loads (Radio) Dual Current Sensor, Low O Single Current Sensor or oc op o<sup>k</sup> o Temperature Sensor L +24V Remote Sense M +12V Remote Sense . N Ground Remote Sense \* See -LVD option description

The monitor output from the unit is a through a Deutsch brand connector P/N: HDP24-18-14PN. The mating connector is the Deutsch P/N: HDP26-18-14SN housing with Deutsch P/N: 1062-16-0622 socket contact.

#### Low State of Charge (SOC) Disconnect (-LVD Option, Terminal F)

The -LVD option provides an output signal that can be coordinated with vehicle software to disconnect parasitic loads based on the State of Charge (SOC) of the 24V batteries. This will protect the batteries from excessive discharge and ensures reserve capacity for engine cranking. The SOC for initiating the output signal is user configurable via Vanner's Dashboard software. Battery aging and temperature variations are compensated for to ensure accurate SOC calculations.

For a typical application, a disconnect request will be sent via CAN message to the vehicle after a combination of extended vehicle inactivity and low SOC. If the multiplex system complies and shuts down, the Equalizer will send a pulse via Terminal F to activate a disconnect. The disconnect, for example, could be a bi-stable magnetic device. Reconnection of the battery shall be achieved through a separate mechanism.

#### Remote Sense (Terminals M, N, and P)

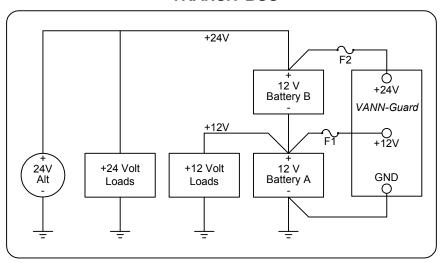
There are three inputs for this function, +24, +12, and ground. They are for remote sense of the battery voltage. This makes the Equalize function insensitive to wire, fuse and connection voltage drops. All three sense lines must be connected for this function to work properly. It is usual for the battery connections to be brought to a distribution point from where connections are made to the rest of the vehicle. Since the battery charge current is the only current which the battery cables carry for most of the time it is convenient to connect the sense wires to these distribution points. This should not introduce a significant error. In fact, when the system stabilizes and the batteries are charged there will be almost no error.

The sense wires can be 16 or 18AWG as the input impedance is high, and the wire gauge can be set for mechanical strength requirements. This allows cost savings and freedom of configuration in the Equalizer power connection wiring, and more freedom in Equalizer location. The equalizer current carrying wire gauge can be the minimum size listed in this manual's wire size table for a given Equalizer rating, up to four times the distance listed. This sets a maximum voltage drop of 0.4V which is reasonable from efficiency and fault detection considerations.

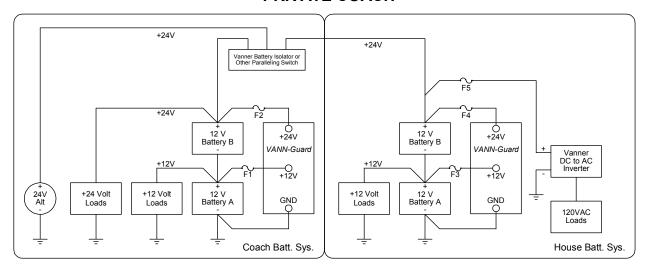
### **Typical Applications**

Vanner VANN-Bus CAN Power Management Systems are used in many types of applications including transit and tour buses, private coaches, heavy trucks and off highway equipment, yachts, and alternative energy systems such as solar powered homes. In addition to VANN-Buses, Vanner manufactures a wide range of complementary products such as DC to DC converters, DC to AC inverters, battery charger/conditioners, and battery isolators. The following system diagrams illustrate how these products are used in various applications.

#### TRANSIT BUS



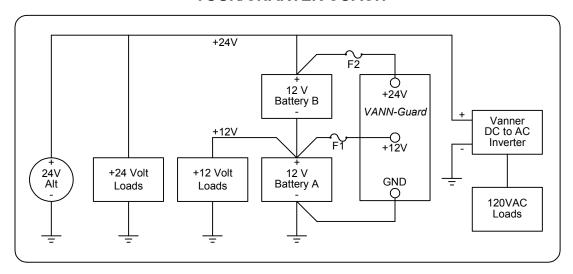
#### **PRIVATE COACH**



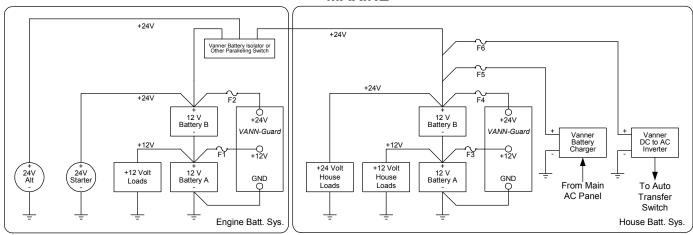


Applications Continued:

#### **TOUR/CHARTER COACH**



#### MARINE





### **Installation Instructions**

These symbols are used to note procedures that if not closely followed could lead to loss of life or damage to equipment or property due to electrocution.



**Electrocution hazard exists** 



Fire hazard exists



A potentially dangerous condition



**Explosive hazard exists** 



Corrosive hazard exists

<u>Do not exceed the specified torque of 120 in-lbs.</u> when connecting cables to the terminal posts (+24, GND, +12) during installation of all the VANN-Bus Models. Torque values higher than specified may damage the product, reduce performance, and/or create hazardous conditions. Products damaged by improper torque are not covered by the warranty.



Do not connect more than one conductor per terminal post on any Vanner VANN-Bus.

Multiple wires and cables may overstress internal components, resulting in poor performance or creating hazardous conditions. Products damaged by the installation of multiple conductors per post are not covered by the warranty.





Fault protection devices must be installed between the VANN-Bus and the power source (battery). A fault protection device would be any fuse or circuit breaker properly rated for the maximum DC current obtainable. This advisory is in accordance with SAE, NEC and UL, for mobile power applications. Install per applicable codes or within 18" of the battery. See Wire and Fuse Sizing Chart on page 10 of this manual or contact Vanner at 1-800-227-6937 or pwrsales@vanner.com if assistance is needed in sizing fault protection devices.







Caution: This equipment tends to produce arcs and sparks during installation. To prevent fire or explosion, compartments containing batteries or flammable materials must be properly ventilated. Safety goggles should always be worn when working near batteries

**Mounting Location** –The *VANN-Bus* may be mounted in any orientation, on a flat mounting surface suitable to support the *VANN-Bus* during application. Do not mount in zero-clearance compartment that may result in the *VANN-Bus* overheating. Locate so that contact by people is unlikely.

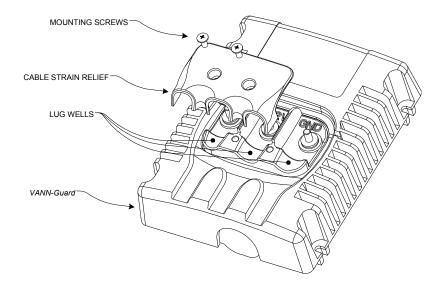
10



**Environmental Protection** – Your *VANN-Bus* has been designed to withstand direct exposure to rain and moisture. The *VANN-Bus* has also been tested for exposure to direct pressure spray, but continual exposure to direct pressure spraying may reduce the *VANN-Bus* serviceable life. Any damage due to water contamination is covered by Vanner only through the terms of our factory warranty.

**Wiring Sequence**— The *VANN-Bus* is internally protected for reverse polarity. The wiring sequence is not an issue with the *VANN-Bus* products.

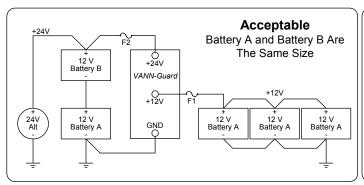
**Strain Relief** – The *VANN-Bus* has an integral strain relief. The *VANN-Bus* is designed with wells for the lug to sit into to resist bolt loosening from cable movement, and the strain relief is designed to further inhibit cable movement. The diagram below shows the proper orientation for the attachment of the strain relief and the #10-32 mounting hardware that is supplied.

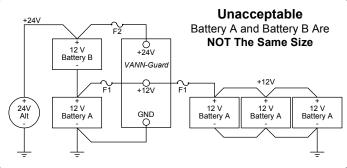






### Caution adding 12volt batteries



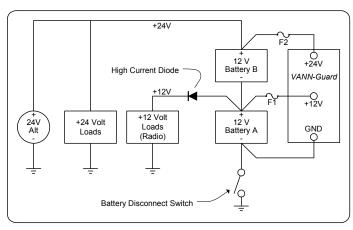


In certain applications, such as private coach or alternate energy applications, it may be desirable to have additional 12 volt "House Batteries" to operate heavy 12 volt (inverter) loads. Use the *VANN-Bus* to charge the additional batteries.

Connect the *VANN-Bus* 12V terminal to the additional batteries only. Do not connect the *VANN-Bus* 12V terminal to both battery banks as this would make Battery A larger than Battery B. **Damage to Battery B may occur during charging** due to overcharging, if the VANN-Bus cannot keep up with the charging system.



### Caution using a Ground-Side Battery Disconnect Switch



The system must be wired as shown to prevent Reverse Polarity Damage to polarity sensitive12 volt loads while the ground-side disconnect switch is open. The *VANN-Bus*'s GND terminal <u>must</u> be wired to the battery side of the ground-side disconnect switch circuit for the *VANN-Bus* to work properly.

Install the external High Current Diode, such as Vanner Model 52-75 (45 amp continuous rating) to protect polarity sensitive 12 volt loads if these loads do not already contain input diode protection. This prevents a reverse polarity on the 12 volt equipment when the battery switch is open. The reverse polarity does not come from the *VANN-Bus*, but from any 24 volt equipment that may be turned ON.



### Wire Size and temperature rating

Cables connecting the *VANN-Bus* to the batteries must be sufficiently sized to prevent unwanted voltage drops. These voltage drops (loss) must be less than 0.05 VDC between the *VANN-Bus's* +24 volt terminal and the battery +24 volt terminal (Battery B positive terminal), less than 0.10 VDC between the *VANN-Bus's* +12 volt terminal and the battery +12 volt terminal (the jumper between Battery A and Battery B), and less than 0.05 VDC between the *VANN-Bus's* GND terminal and the battery ground terminal (Battery A negative terminal that is connected to chassis ground). In most installations, the *VANN-Bus's* terminals are wired directly to the battery terminals (reference fault protection) to prevent voltage loss that could occur in switch contacts, connections, and long wire runs. Since the *VANN-Bus* can be operated in temperatures up to 75°C, use wire rated at least 90°C. See Wire and Fuse Size Chart.

#### Wire and Fuse Size Chart

Wire	Ring Terminal AMP or UL recognized equal	Max wire length, in feet, between <i>VANN-Bus</i> and battery to keep voltage drop under 0.1 volt. The chart assumes wire carries no other load and wire temperature is below 80°C.			
Size AWG		80-60CAN	80-80CAN	80-100CAN	2 X 80-100CAN
#8	33462	2.1	XXX	XXX	XXX
#6	33466	3.2	2.4	XXX	XXX
#4	33470	5.9	4.4	3.5	XXX
#2	322870	8.7	6.5	5.2	2.6
#1	321867	10.9	8.2	6.5	3.3
#1/0	321867	13.8	10.4	8.3	4.1
#2/0	321870	17.6	13.2	10.5	5.3
Fuse F1		80 amp	100 amp	125 amp	250 amp
Fuse F2		40 amp	50 amp	80 amp	150 amp

Crimp the ring terminals using AMP ROTA-CRIMP 600850 (2/0 - 8ga).

**AMP** Product Information Center: 800-522-6752 **AMP** Tooling Assistance Center: 800-722-1111

**Note:** The wire gages listed are for use without remote sense; see the monitor section for applications using the remote sense capability.

### **Testing and Troubleshooting**









CAUTION

Servicing of electrical systems should only be performed by trained and qualified technical personnel.

#### **Equipment Required**

VoltMeter having 0.01 volt resolution. (Fluke Model 87 Multimeter recommended). Clamp-on current meter (Fluke Model 36 Clamp-on Meter recommended).

#### Vanner Repair Service

Vanner offers a quick turn around factory repair service. Send the unit to the address below with a note instructing us to repair it. Include your name, phone number, shipping address (not a P.O. Box Number), and your purchase order number.

# Test Procedure for *VANN-Bus* 80-Series CAN Power Management Systems

The VANN-Bus is working properly if:

- 1. The 12 volt DC loads are being operated continuously and are within the rated capacity of the VANN-Bus and:
- 2. Battery A voltage is lower than Battery B by no more than 0.05 to 0.10 volts (measured at the VANN-Bus's +24, +12 and GND terminals).

Vanner VANN-Buses are electronically protected against reverse polarity damage therefore the DC connection sequence is not an issue.

Vanner *VANN-Buses* will not function properly unless all three battery connections are made. Battery A and Battery B voltages both must be above 8 volts for the unit to turn ON.

Vanner VANN-Buses may be used in parallel with other VANN-Buses and Vanner Equalizer models.

Please note that the 24V, 12V and GND stud position and orientation are different on *VANN-Bus* 80-Series than on other Vanner Equalizers.

#### **VANN-Bus Test Procedure:**

- 1. Field-test the equalizer while fully connected to the vehicle batteries. For bench testing, two 12 volt batteries, or two 12 volt power supplies are required. The *VANN-Bus* must be connected to the batteries at GND, 12V and 24V to function properly.
- 2. If battery voltage is below 24 volts start the vehicle or apply a 24 volt battery charger to the batteries.
- Turn ON 12 volt DC loads up to the VANN-Bus's rated capacity. Measure DC current on the VANN-Bus +12V cable to verify load current.
- 4. At the VANN-Bus measure and record:
  - a. Battery A voltage (voltage between the *VANN-Bus*'s +12 and GND terminals)
  - b. Battery B voltage (voltage between the VANN-Bus's +24 and +12 terminals)
- 5. Subtract Battery A voltage from Battery B voltage and compare readings.



Voltage Comparison		VANN-Bus Status	
a.	Battery A is lower than Battery B but within 0.05 volt.	OFF	Stand-by Mode. The VANN-Bus will not turn ON until Battery A is lower than Battery B by more than 0.05 volts.
b.	Battery A is lower than Battery B by 0.05 to 0.10 volts.	ON	Normal Operating Mode
C.	Battery A is lower than Battery B by more than 0.10 volts	ON	Self-Protection Mode due to Overload Condition. See below.
d.	Battery A is lower than Battery B by more than 0.10 volts	OFF	The VANN-Bus is not functioning properly.
e.	Battery A is higher than Battery B	Abnormal condition. Suspect Battery B is defective or a 12 volt load is connected to Battery B.	

#### **Overload Condition**

An overload condition exists when the 12 volt loads exceed the *VANN-Bus's* rated capacity. The overload condition will not damage the *VANN-Bus*, but may cause damage to the batteries.

During the overload, the *VANN-Bus's* output is limited by internal protection circuits to its Rated Output Amps. The 12 volt amps exceeding the *VANN-Bus's* output are drawn from Battery A which will begin to draw the batteries out of balance. The *VANN-Bus's* full Rated Output Amps are maintained as long as Battery A and Battery B remain balanced within 0.10 volt. The internal protection circuits will reduce the *VANN-Bus's* output as the batteries become further out-of-balance. If Battery A voltage falls below approximately 8 volts the *VANN-Bus* will shut itself OFF.

To correct the overload condition the 12 volt load must be reduced or the VANN-Bus's rated capacity must be increased.

#### Trouble Shooting an Engine No-Start Situation

#### Situation:

A coach has dead batteries and won't start while jump starting. The coach is equipped with a 24 volt starting and charging system, a 12 volt electronic diesel engine control, a *VANN-Bus*, and a moderate 12 volt load which cannot be turned OFF. The coach sits for several days and the batteries run completely dead. During jump-starting the engine cranks but does not start due to low voltage on the 12 volt supply. Electrical testing reveals there is no 12 volt output from the *VANN-Bus* while jump starting even though the *VANN-Bus* separately tests OK.

#### Cause:

The 12 volt load which could not be turned OFF first ran both batteries down until the *VANN-Bus* shut itself OFF due to low voltage. (The *VANN-Bus* will shut OFF if system voltage falls below 16 volts or if voltage on either battery falls below 8 volts.) Then Battery A alone was drained to near zero volts. As the bus is being jumped, 12 volt loads hold Battery A voltage too low for the *VANN-Bus* to turn ON and Battery A is too weak to support the 12 volt electronic engine control.

#### Solution:

Turn OFF all 12 volt loads (turning the battery disconnect switch OFF may accomplish this). Connect the jumper cables but do not crank the engine for two or three minutes. (Both batteries must rise above 8 volts.) The battery disconnect switch can then be turned ON and the bus should have adequate 12 volt power to start.



### **CAN Bus Specification**

A comprehensive CAN communication specification is available. Please contact Vanner's engineering department to ensure you have the latest revision.



**Notes:** 



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